

Build a Raspberry Pi with Node-RED and Industrial GPIO

Introduction

NOTE: This technical note was originally a [blog post on opto22.com](#). We've reproduced the blog post here for your convenience.

The [Raspberry Pi](#)® is an unquestionably powerful computer for just \$35. And it really is just that: a computer. That means the Pi is capable of many tasks and perfect for many automation applications.

[Couple the Pi to industrial, solid-state digital inputs and outputs](#), and you can build compelling and cost-effective solutions for commercial and industrial applications, too.

One of the easiest and fun ways to quickly build software applications is with [Node-RED](#), the free, open-source software tool designed by IBM® Emerging Technologies and used for wiring together hardware devices, APIs, and online services in new and interesting ways.

However, Node-RED is only included in the full PIXEL GUI version of the [Raspbian Jessie Operating System](#), available from [raspberrypi.org](#). Their latest [2016-11-25-raspbian-jessie-lite.img](#) build for **headless operation** (no monitor, keyboard, or mouse required) is no longer bundled with either Node-RED or the required software tools node.js and npm.

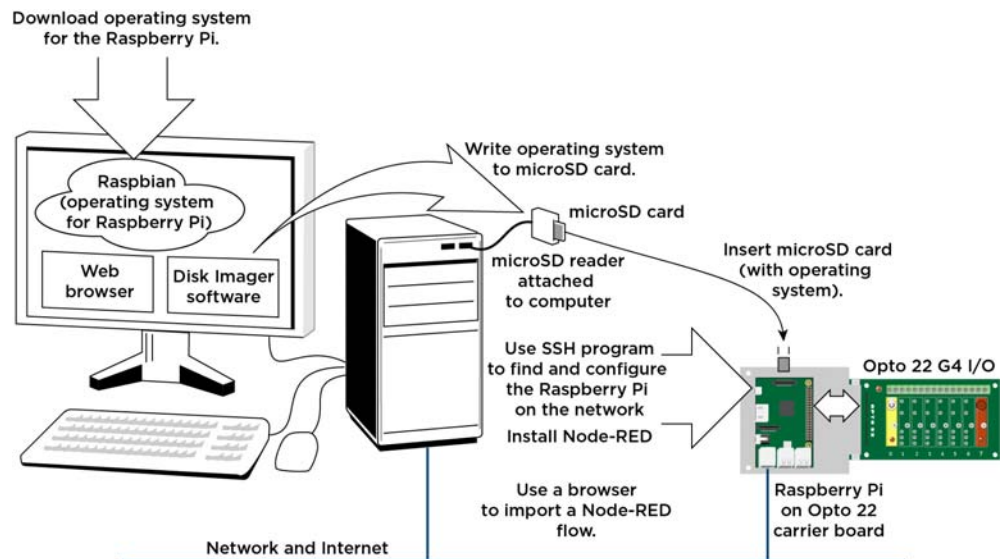
The purpose of this post is to guide you through creating a headless Raspberry Pi computer with the latest versions of Node-RED, node.js, and npm, building a Node-RED application, and controlling and sensing GPIO connected to industrial digital I/O, quickly and simply. This example uses the Opto 22 [Digital I/O for Raspberry Pi Starter Kit](#).



This post provides step-by-step instructions for:

- Building and configuring your microSD boot image with Raspbian Jessie Lite
- Installing Node-RED, node.js, and npm
- Configuring Node-RED to start up at boot time
- Installing various Node-RED nodes, including our SNAP PAC Node-RED nodes (optional)
- Importing a Node-RED flow for sensing and controlling digital I/O through GPIO nodes

Here is a diagram of the steps you'll take:



What you'll need:

- A Raspberry Pi—I'm using a Raspberry Pi 3
- A microSD card (minimum 8 GB) and reader for your computer
- A power supply

Optional items used in this post (needed to see the result of a Node-RED flow with GPIO nodes):

- A [Digital I/O for Raspberry Pi Starter Kit](#)—includes carrier board, rack, and four I/O modules

Now, I'm no expert with the Raspberry Pi or the Linux command line. You don't need to be, either. I think you'll find the following instructions pretty easy to do if you're careful to follow the steps in order.

When you're done, you'll have yourself a complete, powerful, and exciting computing platform to build the automation application of your dreams.

Step 1: Build and Configure Raspbian microSD boot device

1. Download Raspbian Jessie Lite image for headless operation (no monitor, keyboard, or mouse needed): https://downloads.raspberrypi.org/raspbian_lite_latest
2. Unzip the file into your /Downloads folder.

Instructions for OS X from Terminal window:

```
diskutil list
```

Determine microSD disk name from result (for example, for disk4):

```
diskutil unmount disk4s1  
cd downloads/
```

Choose one (1st for Jessie; 2nd for Jessie Lite):

```
sudo dd bs=1m if=2016-11-25-raspbian-jessie.img of=/dev/rdisk4  
sudo dd bs=1m if=2016-11-25-raspbian-jessie-lite.img  
of=/dev/rdisk4
```

Instructions for Windows:

- Download Win32 Disk Imager: <https://sourceforge.net/projects/win32diskimager/>
- Install and start Win32 Disk Imager.
- Select image file from your Downloads folder, and choose the drive letter for your SD card.
- Click Write.

UPDATE: The latest Raspbian Jessie image from raspberrypi.org (016-11-25-raspbian-jessie-lite.img) no longer allows SSH connections by default. You must place a file with no extension named "ssh" in the root of the card. To do this, simply create a new Text Document on your desktop with no contents, then rename the file to remove the extension. Copy this file onto your microSD card in the /BOOT/ directory. Now, you can SSH in as shown in the next step.

Step 2: Log in and Configure Headless Pi

We're using the command prompt method for headless operation under Jessie Lite

NOTE: this step could be problematic if more than one Raspberry Pi3/Raspbian Jessie in its default configuration exists on your network or if your DNS cache isn't flushed. If your connection is refused, see update in previous step.

1. Log in:

Mac/Linux: Attempt SSH session from your terminal application:

```
ssh pi@raspberrypi
```

Windows: You'll need the free PuTTY terminal application download. Once installed, enter raspberrypi in the Host Name (or IP address) field. Make sure the port number is 22 and SSH option is selected, then click Open.

2. Once connected, log in:
Mac/Linux: pi@raspberrypi's password: `raspberrypi`
Windows: login as: `pi`
pi@raspberrypi's password: `raspberrypi`
3. At the command prompt, enter: `sudo raspi-config`
4. Select Option 1 - Expand Filesystem
5. Select Option 2 - Change User Password (for example, `opto22`)
6. Select Option 9 - Advanced Options; select option A2 - Change Hostname (example: `rpi-g4pb8h-benson`)
7. Select Option 5 - Internationalisation Options (example for user in California):
Locales: `en_US.UTF-8 UTF-8`
Timezone: `US, Pacific Ocean`
Change Wi-Fi Country: `us` (press "U" to get close)
8. Select `<Finish>` and then select **yes** when prompted for reboot.
9. Log back in with new Hostname (example: `ssh pi@rpi-g4pb8h-benson`).
10. Enter your new password.

Step 3: Install Node.js, npm, and Node-RED

```
sudo su -
curl -sL https://deb.nodesource.com/setup_6.x | sudo bash -
apt-get install nodejs -y
node -v (returns v6.9.2 or higher)
npm -v (returns 3.10.9 or higher)
npm cache clean
npm install -g --unsafe-perm node-red
exit
node-red
```

At this point, confirm that Node-RED is running by navigating with your browser to your Pi and port 1880:

```
http://[hostname]:1880 (example: http://rpi-g4pb8h-benson:1880)
```

Step 4: Build your first Node-RED app

Note: This step and the next exercise are important for two reasons: (1) They confirm that everything is installed properly; and (2) They create the appropriate folders for the remaining steps.

1. Click and drag an Inject node to the palette.
2. Drag a Debug node to the palette.

3. Wire the two nodes together.
4. Click Deploy in the upper-right corner of Node-RED.
5. Click the Debug tab beneath the Deploy button.
6. Finally, click the tab emerging from the left of the Inject node. You should see the current time (in Epoch time) in the debug pane.

Now go back to your terminal session, and issue the following command:

```
ctrl-c (to shut down Node-RED)
sudo shutdown -P now
```

This final command immediately shuts down your Pi with the Poweroff parameter, finishes disk writes, and requires you to remove and reinstall power to boot back up again. This is a safety measure to make sure all of your work up to this point is saved to the microSD card. Always wait for the green LED on the Pi to go out completely before removing power.

NOTE: I highly recommend always using the `shutdown` command to preserve your Pi file system if you intend to power down the system. If you'd rather just reboot the Pi, use:

```
sudo shutdown -r now
```

Step 5: Install SNAP PAC Node-RED Nodes (optional)

The SNAP PAC Node-RED nodes offer a simple method for querying and controlling a SNAP PAC I/O System. You can use a SNAP PAC I/O system to gather and control analog, serial, and other digital I/O data not covered by any G4 and SNAP digital I/O connected to the GPIO of the Pi.

NOTE: If you've installed Node-RED on your existing Pi separately from the above instructions, be sure you have node.js version 4.4.5 or later installed first. This is the minimum supported version to use Opto 22's SNAP PAC Node-RED nodes. You can determine node's version with the following command: `node -v`

```
pwd (should result in /home/pi)
cd .node-red
npm install node-red-contrib-pac
```

Step 6: Set up Node-RED to start up at boot

The Node-RED recommended method is to install Node-RED Service:

```
sudo su -
wget
https://raw.githubusercontent.com/node-red/raspbian-deb-package/master
/resources/nodered.service -O /lib/systemd/system/nodered.service
wget
https://raw.githubusercontent.com/node-red/raspbian-deb-package/master
/resources/node-red-start -O /usr/bin/node-red-start
```

```
wget
https://raw.githubusercontent.com/node-red/raspbian-deb-package/master
/resources/node-red-stop -O /usr/bin/node-red-stop
chmod +x /usr/bin/node-red-st*
systemctl daemon-reload
systemctl enable nodered.service
shutdown -r now
```

When the Pi reboots, Node-RED should be running. Access the Node-RED environment from your web browser here:

[http://\[hostname\]:1880](http://[hostname]:1880) (for example, <http://rpi-g4pb8h-benson:1880>)

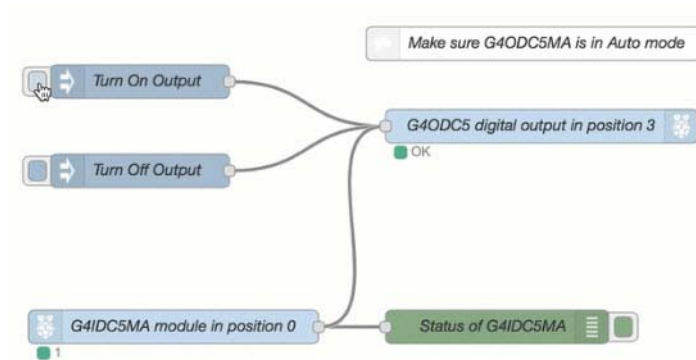
When installing new nodes from the command line, start/stop Node-RED by using the Node-RED service commands:

```
node-red-stop
node-red-start
```

Step 7: Import a GPIO-based Node-RED flow to test I/O

This final step involves importing a Node-RED flow I've created to test the GPIO nodes and the corresponding I/O modules on the rack. (This test flow will work either with or without the rack and I/O modules.)

Power up your Pi, and log into Node-RED. Then we'll import this flow:



To import this flow, go to your Node-RED application ([http://\[hostname\]:1880](http://[hostname]:1880)), click the hamburger icon in the top right, select "Import", then "Clipboard" and choose the New Flow button. Next, copy and paste this code into the resulting window:

```
[{"id":"d95eb067.d4687","type":"inject","z":"aa9ee7c0.e8cd88","name":"Turn On Output","topic":"","payload":"","payloadType":"num","repeat":"","crontab":"","once":false,"x":300,"y":180,"wires":[["878648ac.fc2948"]]}, {"id":"878648ac.fc2948","type":"rpi-gpio out","z":"aa9ee7c0.e8cd88","name":"G4ODC5 digital output in position 3","pin":"35","set":"","level":"0","out":"out","x":660,"y":220,"wires":[]}, {"id":"7d18b79f.0fa588","type":"inject","z":"aa9ee7c0.e8cd88","na
```

```
me": "Turn Off
Output", "topic": "", "payload": "1", "payloadType": "num", "repeat": "", "cron
tab": "", "once": false, "x": 300, "y": 260, "wires": [[ "878648ac.fc2948" ] ] }, {
id": "82511eef.33cbb", "type": "rpi-gpio
in", "z": "aa9ee7c0.e8cd88", "name": "G4IDC5MA module in position
0", "pin": "40", "intype": "tri", "debounce": "25", "read": false, "x": 330, "y":
400, "wires": [[ "6f379125.5007d", "878648ac.fc2948" ] ] }, { "id": "6f379125.50
07d", "type": "debug", "z": "aa9ee7c0.e8cd88", "name": "Status of
G4IDC5MA", "active": true, "console": "false", "complete": "payload", "x": 620
, "y": 400, "wires": [ ] }, { "id": "2e694694.1487aa", "type": "comment", "z": "aa9
ee7c0.e8cd88", "name": "Make sure G4ODC5MA is in Auto
mode", "info": "", "x": 652.5, "y": 146, "wires": [ ] }
```

Finally, click Import. Now, position the nodes on the canvas where you like, and you're done. Click the Deploy button to deploy this flow to your Pi.

Now, you can click the left side of the Inject button named "Turn On Output" and you should see the value under the node named "G4ODC5 digital output in position 3" change to "0". Click the Inject button named "Turn Off Output", and the value will change to one.

If this result seems inverted to you, it's because Opto 22 solid-state I/O modules are negative-true logic: Write a 0 to turn on; write a 1 to turn off.

To see this in live action, I've used the new [Digital I/O for Raspberry Pi Starter Kit](#) (available for a limited time at \$99). I placed my own Raspberry Pi3 (I purchased mine at [Amazon.com](#)) on the assembled Starter Kit atop the [OPTO-P1-40P](#) carrier board and attached that to the [G4PB8H](#) mounting rack. Then, I inserted each of the 4 modules in the orientation shown in the photo on page 1. That puts my DC input module ([G4IDC5MA](#)) in position 0 on the rack, and the DC output module ([G4ODC5](#)) in position 3.

I connected the system to an Ethernet network, and powered it up using my Pi power supply (wall wart).

Note that this test flow will work without the rack and I/O modules. You just won't be able to see the LEDs positively indicate everything is working properly. In the [blog post](#) you can see a short video I took with my phone, showing what happens on the rack when I flip the switch on the input, and the resulting output module firing.

If you have the Starter Kit and followed all of the instructions above, you can turn the G4ODC5 on and off from software (Node-RED). Simply click the Inject button on the left of the nodes labeled Turn On Output and Turn Off Output.

All done!

Congratulations! You've just built a fully configured, latest-build Raspberry Pi computer with Node-RED and the ability to interface with real-world electrical loads using the Pi's GPIO pins.

Let me know how your installation went in the [comments section of the blog](#). I'd also love to hear any tips, comments, suggestions, or complaints, too!

Thanks for reading. See the next page for additional nodes you may want to install.

BONUS: Other nodes you may find useful

There are hundreds of Node-RED nodes available from npm and flows.nodered.org. Here are a few I've found useful for various tasks. There are two ways to install these nodes.

The preferred method is from within Node-RED. From the hamburger menu at the top right, select Manage Palette. Then click the Install tab in the left pane. You can search by the name of the node listed below, and click the small Install button.

If you prefer, you can also install from the command line. Use these steps:

1. Establish an SSH session to your RPi.
2. Navigate to your .node-red folder (usually found under /home/pi folder):
`cd .node-red`

Bigtimer—timer with dusk, dawn, months, days, manual override, schedule pause, and more

```
npm install node-red-contrib-bigtimer
```

Ping—for taking input and pinging devices on a network

```
npm install node-red-configurable-ping
```

MSSQL—for establishing a connection to a Microsoft SQL Server instance, locally or in the cloud.

```
npm install node-red-contrib-mssql
```

MySQL—for connecting to and exchanging data with MySQL databases

```
npm install node-red-node-mysql
```

M2X—for connecting to and interfacing with AT&T's M2X IoT Platform

```
npm install node-red-m2x
```

Bluemix—various nodes for interfacing with the IBM Bluemix® IoT platform

```
npm install node-red-bluemix-nodes
```

Aggregator—for aggregating numeric values over a specific time span, including mean, median, min, max

```
npm install node-red-contrib-aggregator
```

Moment—produces a nicely formatted Date/Time string

```
npm install node-red-contrib-moment
```

SNMP—for fetching either individual oids, or a table oid from an SNMP-enabled host

```
npm install node-red-node-snmp
```

Weather Underground—for getting the current weather conditions and forecast

```
npm install node-red-node-weather-underground
```

Dropbox—to send and receive files from Dropbox cloud

```
npm install node-red-node-dropbox
```

Modbus TCP—to communicate with Modbus/TCP devices over Ethernet.

```
npm install node-red-contrib-modbus
```


Sparkplug—to communicate with Cirrus Link or Ignition MQTT servers with Sparkplug protocol

```
npm install node-red-contrib-sparkplug
```

To install all these nodes at once:

```
cd .node-red
node-red-stop
npm install node-red-contrib-bigtimer node-red-configurable-ping
node-red-contrib-mssql node-red-node-mysql node-red-m2x
node-red-bluemix-nodes node-red-contrib-moment node-red-node-snmp
node-red-node-weather-underground node-red-node-dropbox
node-red-contrib-modbus node-red-contrib-sparkplug
node-red-start
```